

# Einige Lösungen zu Mathe 2/ Übung 2

## Teil 1

In[2]:= **(\* 1 \*)**

In[3]:= **A = {{1, 2}, {3, 4}}**

Out[3]= {{1, 2}, {3, 4}}

In[4]:= **A // MatrixForm**

Out[4]/MatrixForm=

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$$

In[5]:= **B = {{0, 1}, {-1, 0}}**

Out[5]= {{0, 1}, {-1, 0}}

In[6]:= **B // MatrixForm**

Out[6]/MatrixForm=

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

In[7]:= **-2 A // MatrixForm**

Out[7]/MatrixForm=

$$\begin{pmatrix} -2 & -4 \\ -6 & -8 \end{pmatrix}$$

In[8]:= **A - B // MatrixForm**

Out[8]/MatrixForm=

$$\begin{pmatrix} 1 & 1 \\ 4 & 4 \end{pmatrix}$$

In[9]:= **A.B // MatrixForm**

Out[9]/MatrixForm=

$$\begin{pmatrix} -2 & 1 \\ -4 & 3 \end{pmatrix}$$

In[10]:= **B.A // MatrixForm**

Out[10]/MatrixForm=

$$\begin{pmatrix} 3 & 4 \\ -1 & -2 \end{pmatrix}$$

In[11]:=

**(\* 2 \*)**

In[12]:= **(\* a \*)**

In[13]:= **Y = {{2, I}, {-I, 3}}**

Out[13]= {{2, i}, {-i, 3}}

In[14]:= **Z = Inverse[Y]**

Out[14]=  $\left\{ \left\{ \frac{3}{5}, -\frac{i}{5} \right\}, \left\{ \frac{i}{5}, \frac{2}{5} \right\} \right\}$

In[15]:=

In[16]:= **g1 = {i1, i2} == Y.{u1, u2}**

Out[16]=  $\{i1, i2\} == \{2 u1 + i u2, -i u1 + 3 u2\}$

In[17]:= **Solve[g1, {u1, i1}] // Expand**

Out[17]=  $\{\{u1 \rightarrow i i2 - 3 i u2, i1 \rightarrow 2 i i2 - 5 i u2\}\}$

In[18]:= **(\* daraus liest man ab: \*)**

In[19]:= **K = {{-3 I, I}, {-5 I, 2 I}}**

Out[19]=  $\{\{-3 i, i\}, \{-5 i, 2 i\}\}$

In[20]:=

**(\* b \*)**

In[21]:= **Kgesamt = K.K**

Out[21]=  $\{\{-4, 1\}, \{-5, 1\}\}$

In[22]:= **% // MatrixForm**

Out[22]/MatrixForm=

$$\begin{pmatrix} -4 & 1 \\ -5 & 1 \end{pmatrix}$$

## Teil 2

In[23]:= **(\* 4 \*)**

In[24]:=

In[25]:= **A = {{3, 1}, {-1, 2}}**

Out[25]=  $\{\{3, 1\}, \{-1, 2\}\}$

In[26]:= **% // MatrixForm**

Out[26]/MatrixForm=

$$\begin{pmatrix} 3 & 1 \\ -1 & 2 \end{pmatrix}$$

In[27]:= **c = {2, 1}**

Out[27]=  $\{2, 1\}$

In[28]:= **{x, y} = Inverse[A].c**

Out[28]=  $\left\{ \frac{3}{7}, \frac{5}{7} \right\}$

In[29]:= **x**

Out[29]=  $\frac{3}{7}$

In[30]:= **y**

Out[30]=  $\frac{5}{7}$

In[31]:=

**(\* 5 \*)**

In[32]:= **(\* a \*)**

In[33]:= **A = {{s, 1}, {-1, 2}}**

Out[33]= {{s, 1}, {-1, 2}}

In[34]:= **% // MatrixForm**

Out[34]//MatrixForm=

$$\begin{pmatrix} s & 1 \\ -1 & 2 \end{pmatrix}$$

In[35]:= **Solve[Det[A] == 0, s]**

Out[35]=  $\left\{ \left\{ s \rightarrow -\frac{1}{2} \right\} \right\}$

In[36]:= **(\* b \*)**

In[37]:= **s = 2**

Out[37]= 2

In[38]:= **A**

Out[38]= {{2, 1}, {-1, 2}}

In[39]:= **x = {1, 2}**

Out[39]= {1, 2}

In[40]:= **y = A.x**

Out[40]= {4, 3}

In[41]:= **x = {0, -1}**

Out[41]= {0, -1}

In[42]:= **y = A.x**

Out[42]= {-1, -2}

In[43]:=

### Teil 3

In[44]:= **(\* 7 \*)**

In[45]:= **A** = {{1, 3, 2}, {0, 1, 0}, {2, 0, 1}}

Out[45]= {{1, 3, 2}, {0, 1, 0}, {2, 0, 1}}

In[46]:= (**\* die Inverse, also Ergebnis für a & c \***)

In[47]:= **Ainv = Inverse[A]**

Out[47]=  $\left\{ \left\{ -\frac{1}{3}, 1, \frac{2}{3} \right\}, \{0, 1, 0\}, \left\{ \frac{2}{3}, -2, -\frac{1}{3} \right\} \right\}$

In[48]:= **Ainv // MatrixForm**

Out[48]//MatrixForm=

$$\begin{pmatrix} -\frac{1}{3} & 1 & \frac{2}{3} \\ 0 & 1 & 0 \\ \frac{2}{3} & -2 & -\frac{1}{3} \end{pmatrix}$$

In[49]:= (**\* b \***)

In[50]:= **Det[A]**

Out[50]= -3

In[51]:= (**\* d \***)

In[52]:= **c = {2, 1, 0}**

Out[52]= {2, 1, 0}

In[53]:= (**\* i \***)

In[54]:= **{x, y, z} = Ainv.c**

Out[54]=  $\left\{ \frac{1}{3}, 1, -\frac{2}{3} \right\}$

In[55]:= **x**

Out[55]=  $\frac{1}{3}$

In[56]:= **y**

Out[56]= 1

In[57]:= **z**

Out[57]=  $-\frac{2}{3}$

In[58]:= (**\* ii \***)

In[59]:= **A // MatrixForm**

Out[59]//MatrixForm=

$$\begin{pmatrix} 1 & 3 & 2 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix}$$

In[60]:= **AT = A // Transpose**

Out[60]= {{1, 0, 2}, {3, 1, 0}, {2, 0, 1}}

In[61]:= **AT // MatrixForm**

Out[61]//MatrixForm=

$$\begin{pmatrix} 1 & 0 & 2 \\ 3 & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix}$$

In[62]:= **B1T = {C, {3, 1, 0}, {2, 0, 1}}**

Out[62]= {{2, 1, 0}, {3, 1, 0}, {2, 0, 1}}

In[63]:= **B1 = B1T // Transpose**

Out[63]= {{2, 3, 2}, {1, 1, 0}, {0, 0, 1}}

In[64]:= **B1 // MatrixForm**

Out[64]//MatrixForm=

$$\begin{pmatrix} 2 & 3 & 2 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

In[65]:=  $\begin{pmatrix} 2 & 3 & 2 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

Out[65]= {{2, 3, 2}, {1, 1, 0}, {0, 0, 1}}

In[66]:= **x = Det[B1] / Det[A]**

Out[66]=  $\frac{1}{3}$

In[67]:=

**(\* 9 \*)**

In[68]:= **T = {{0, 0, 1}, {0, 0, 2}, {1, 2, 0}}**

Out[68]= {{0, 0, 1}, {0, 0, 2}, {1, 2, 0}}

In[69]:= **T // MatrixForm**

Out[69]//MatrixForm=

$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 2 \\ 1 & 2 & 0 \end{pmatrix}$$

In[70]:= **(\* a \*)**

In[71]:= **Eigenvalues[T]**

Out[71]=  $\{-\sqrt{5}, \sqrt{5}, 0\}$

In[72]:= **(\* b \*)**

In[73]:= **es = Eigensystem[T]**

Out[73]=  $\left\{ \{-\sqrt{5}, \sqrt{5}, 0\}, \left\{ \left\{ -\frac{1}{\sqrt{5}}, -\frac{2}{\sqrt{5}}, 1 \right\}, \left\{ \frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}, 1 \right\}, \{-2, 1, 0\} \right\} \right\}$

In[74]:= **ew = es[[1]]**

Out[74]=  $\{-\sqrt{5}, \sqrt{5}, 0\}$

In[75]:= **ev = es[[2]]**

Out[75]=  $\left\{ \left\{ -\frac{1}{\sqrt{5}}, -\frac{2}{\sqrt{5}}, 1 \right\}, \left\{ \frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}, 1 \right\}, \{-2, 1, 0\} \right\}$

In[76]:= **(\* der erste Eigenvektor; muss zum ersten Eigenwert gehören: \*)**

In[77]:= **ev1 = ev[[1]]**

Out[77]=  $\left\{ -\frac{1}{\sqrt{5}}, -\frac{2}{\sqrt{5}}, 1 \right\}$

In[78]:= **ew1 = ew[[1]]**

Out[78]=  $-\sqrt{5}$

In[79]:= **(\* Probe: )**



In[79]:= **T.ev1 == ew1 \* ev1**

Out[79]= True

In[80]:= **T.ev1**

Out[80]=  $\{1, 2, -\sqrt{5}\}$

In[81]:= **ew1 \* ev1**

Out[81]=  $\{1, 2, -\sqrt{5}\}$

In[82]:=

**(\* c \*)**

In[83]:= **(\* Einheits-Eigenvektoren \*)**

In[84]:= **ev1n = ev1 / Norm[ev1]**

Out[84]=  $\left\{ -\frac{1}{\sqrt{10}}, -\sqrt{\frac{2}{5}}, \frac{1}{\sqrt{2}} \right\}$

In[85]:= **ev2 = ev[[2]]**

Out[85]=  $\left\{ \frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}, 1 \right\}$

In[86]:= **ev3 = ev[[3]]**

Out[86]=  $\{-2, 1, 0\}$

In[87]:= **ev2n = ev2 / Norm[ev2]**

Out[87]=  $\left\{ \frac{1}{\sqrt{10}}, \sqrt{\frac{2}{5}}, \frac{1}{\sqrt{2}} \right\}$

In[88]:= **ev3n = ev3 / Norm[ev3]**

Out[88]=  $\left\{ -\frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}}, 0 \right\}$

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In[89]:= Cross[ev1n, ev2n].ev3n
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Out[89]= 1
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Die Vektoren bilden also in der Reihenfolge 1,2,3 ein Rechtssystem und spannen das gesuchte neue Koordinatensystem S' auf; sie werden jetzt als Zeilen der Drehmatrix, welche von S nach S' transformiert, benutzt

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In[91]:= d = {ev1n, ev2n, ev3n}
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Out[91]= {{-1/Sqrt[10], -Sqrt[2/5], 1/Sqrt[2]}, {1/Sqrt[10], Sqrt[2/5], 1/Sqrt[2]}, {-2/Sqrt[5], 1/Sqrt[5], 0}}
```

```
(* i *)
```

```
In[92]:= Det[d]
```

```
Out[92]= 1
```

```
(* ii *)
```

```
In[95]:= invd = Inverse[d]
```

```
Out[95]= {{-1/Sqrt[10], 1/Sqrt[10], -2/Sqrt[5]}, {-Sqrt[2/5], Sqrt[2/5], 1/Sqrt[5]}, {1/Sqrt[2], 1/Sqrt[2], 0}}
```

```
In[96]:= transd = Transpose[d]
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Out[96]= {{-1/Sqrt[10], 1/Sqrt[10], -2/Sqrt[5]}, {-Sqrt[2/5], Sqrt[2/5], 1/Sqrt[5]}, {1/Sqrt[2], 1/Sqrt[2], 0}}
```

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In[97]:= invd == transd
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Out[97]= True
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